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# RE 29564-XN-100/04.16

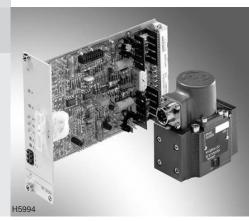
Replaces: 05.10

# Directional servo valve with mechanical position feedback

Type 4WS2EM ...XN...-100

Size 6 Component series 2X Maximum operating pressure 315 bar Maximum flow 48 l/min





# ATEX units – For potentially explosive atmospheres



#### Information on the explosion protection:

- ► Area of application in accordance with the Explosion Protection Directive 2014/34/EU: II 3G; II 3D
- ► Types of protection:
  - Ex nA II T5X according to EN 60079-0 / EN 60079-15
  - Ex tD A22 IP 65 TX according to EN 61241-0 / EN 61241-1

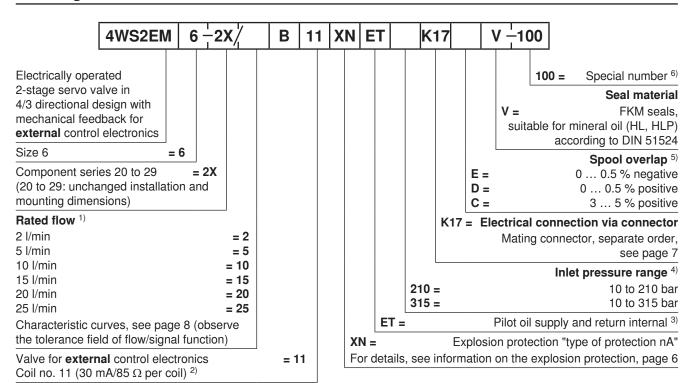
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#### **Features**

- 4/3-way version
- Directional servo valve for intended use in potentially explosive atmospheres of zone 2 and 22
- Valve to control position, force, pressure or velocity
- 2-stage servo valve with mechanical feedback
- 1st stage as nozzle flapper plate amplifier
- For subplate mounting
- Porting pattern according to ISO 4401-03-02-0-05 (but without locating hole)
- Dry control motor, no contamination of the solenoid gaps by the hydraulic fluid
- Can also be used as 3-way version
- Wear-free spool feedback element
- External control electronics in Euro-card format or in modular design (separate order)
- Valve is adjusted and tested
- Pressure chambers at the control sleeve with gap seal, therefore no wear of the seal ring
- Filter for 1st stage freely accessible from the outside

# **Ordering code**



#### 1) Rated flow

The rated flow refers to a 100% command value signal at 70 bar valve pressure differential (35 bar per control edge). The valve pressure differential must be regarded as reference. Other values result in the flow being changed. A possible rated flow tolerance of  $\pm 10\%$  must be taken into account (see flow/signal function on page 8).

# 2) External control electronics

The actuating signal must be created from a flow-controlled output stage. Control electronics (servo amplifier), see page 6.

# 3) Pilot oil

This valve is only available with internal pilot oil supply and return.

# 4) Inlet pressure range

Care should be taken that the system pressure is as constant as possible.

With regard to the dynamics, the frequency response dependency must be observed within the admissible pressure range of 10 ... 210 bar or 10 ... 315 bar.

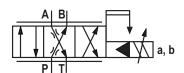
# 5) Spool overlap

The control spool overlap is specified in % of the nominal control spool stroke.

#### 6) Special number "100"

The channels  $P \rightarrow B$  und  $A \rightarrow T$  are open 10% of the nominal quantity without control (de-energized state).

#### **Symbol**



# Function, section

#### 4WS2EM 6-2X/...XN...-100

Valves of this type are electrically operated, 2-stage directional servo valves with porting pattern according to ISO 4401-03-02-0-05. They are mainly used to control position, force, pressure or velocity.

These valves are made of an electro-mechanical converter (torque motor) (1), a hydraulic amplifier (principle: nozzle flapper plate) (2) and a control spool (3) in a sleeve (2nd stage) which is connected with the torque motor via a mechanical feedback.

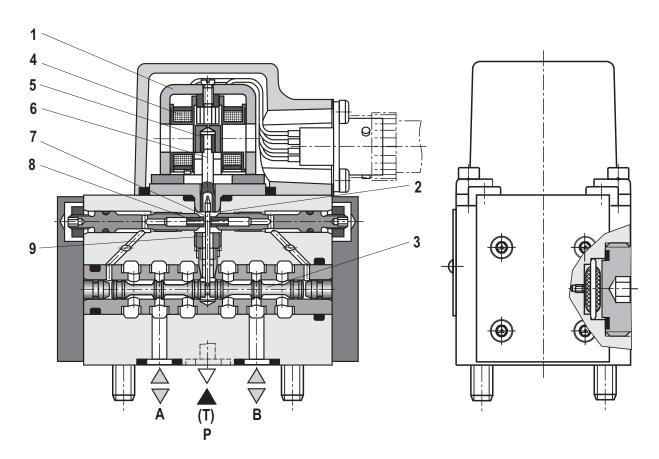
An electrical input signal at the coils (4) of the torque motor generates a force by means of a permanent magnet which acts on the armature (5), and in connection with a torque tube (6) results in a torque. This causes the flapper plate (7) which is connected to the torque tube (6) via a bolt to move from the central position between the two control nozzles (8), and a pressure differential is created across the front sides of the control spool (3). The pressure differential results in the spool changing its position, which results in the pressure port being connected to one actuator port and, at the same time, the other actuator port being connected to the return flow port.

The control spool is connected to the flapper plate or the torque motor by means of a bending spring (mechanical feedback) (9). The position of the spool is changed until the feedback torque across the bending spring and the electromagnetic torque of the torque motor are balanced and the pressure differential at the nozzle flapper plate system becomes zero.

The stroke of the control spool and consequently the flow of the servo valve are regulated proportionally to the electrical input signal. It must be noted that the flow depends on the valve pressure drop.

#### External control electronics (separate order)

External control electronics (servo amplifier) serve the actuation of the valve, amplifying an analog input signal (command value) so that with the output signal, the servo valve is actuated in a flow-controlled form.



Type 4WS2EM 6-2X/...XN...-100

# **Technical data**

general		
Porting pattern		ISO 4401-03-02-0-05
Installation position		Any (ensure that during start-up of the system, the valve is supplied with sufficient pressure (≥ 10 bar)!)
Surface protection	Valve body, cover, filter screw	Nitro-carburated
	Cap	Anodized
Storage temperature	range °C	+5 +40
Ambient temperature	e range °C	−30 +80
Weight	kg	1.1

# **hydraulic** (measured with HLP32, $\vartheta_{oil} = 40 \text{ °C} \pm 5 \text{ °C}$ )

10 210 or 10 315
Pressure peaks < 100 static < 10
Mineral oil (HL, HLP) according to DIN 51524 Ignition temperature > 150 °C
-15 +70; preferably +40 +50
15 380; preferably 30 45
Class 18/16/13 <sup>1)</sup>
$\sqrt{p_{\rm P}/70  \rm bar} \cdot (0.4  \rm l/min + 0.02 \cdot q_{\rm v  nom})^{3); 4)}$
2; 5; 10; 15; 20; 25
120 170
Mechanical
5 ≤ 1.5
5 ≤ 0.2
5 ≤ 0.2
) ≥50
$\leq$ 3, long-term $\leq$ 5
5 ≤1
5 ≤1
· ≤2
· ≤1

The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and at the same time increases the life cycle of the components. For the selection of the filters, see www.boschrexroth.com/filter

<sup>&</sup>lt;sup>2)</sup>  $q_{V,L}$  = zero flow in I/min

 $<sup>^{3)}</sup>$   $q_{\text{v nom}}$  = rated flow in I/min

<sup>&</sup>lt;sup>4)</sup>  $p_P$  = operating pressure in bar

# **Technical data**

Protection class according to EN 60529:1991+A1:2000		IP 65 with mating connector correctly mounted and locke	
Type of signal			Analog
Rated current per coil		mA	30
Resistance per coil		Ω	85
Inductivity with 60 Hz	Serial connection	Н	1.0
and 100% rated current	Parallel connection	Н	0.25

# Information on the explosion protection

Area of application according to directive 2014/34/EU	II 3G; II 3D
Type of protection according to EN 60079-0 / EN 60079-15	Ex nA II T5X
Type of protection according to EN 61241-0 / EN 61241-1	Ex tD A22 IP 65 TX
Maximum surface temperature °C	100
Ambient temperature range °C	−30 +80
Hydraulic fluid temperature range °C	<b>−15 +70</b>
Maximum admissible operating voltage of the servo V amplifier	32 (DC)
Conditions for use in zone 2 and 22	The valve may only be used in potentially explosive atmospheres of device group II, category 3, with a "low" risk of mechanical hazard according to the harmonized standards EN 60079-0 and EN 61241-0.
	For use in zones with a "high" risk of mechanical load according to these standards, precautions for reducing the risk of mechanical loads to "low" have to be taken.

# **External control electronics**

Servo amplifier	Euro-card format	Analog	Type VT-SR2-1X/.60 according to data sheet 29980
(separate order)	Modular design	Analog	Type VT 11021 according to data sheet 29743
The valve coils may only be connected to these amplifiers in parallel!			

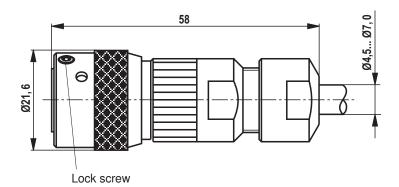
# **⚠ WARNING** – Explosion hazard

- The external servo amplifier must be operated outside the potentially explosive atmosphere!

# **Mating connector**

The servo valve may only be supplied via this mating

Separate order, material no. R901043330



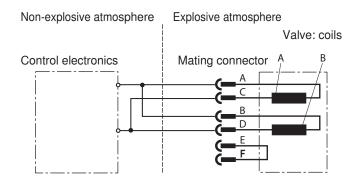
#### Connection:

Contact sockets with litz wire connection cross-section  $0.4 \dots 0.75 \text{ mm}^2$  are enclosed unassembled.

Connection of the litz wires to contact sockets is possible by crimping or soldering.

The tools required for crimping connection are listed in the assembly instructions enclosed with the mating connector.

# **Electrical connection** (parallel connection example)



The coils are connected in parallel in the mating connector or to the amplifier (see figure).

For serial connection, contacts B and C have to be connected.

The bridge E-F can be used for electrical recognition of the correct connection of the connector or for cable break detection.

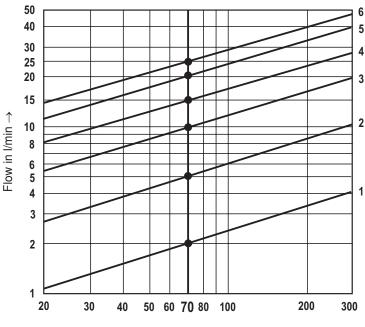
Electrical control from A (+) to D (-) provides for the direction of flow P  $\rightarrow$  A and B  $\rightarrow$  T. Reverse electrical control provides for direction of flow P  $\rightarrow$  B and A  $\rightarrow$  T.

# Characteristic curves (measured with HLP32, $\vartheta_{Oil}$ = 40 °C ± 5 °C)

Flow/load function (tolerance  $\pm 10$  %) with 100 % command value signal

Notice:

Observe the flow values in max. command value range (see tolerance field of the flow/signal function)



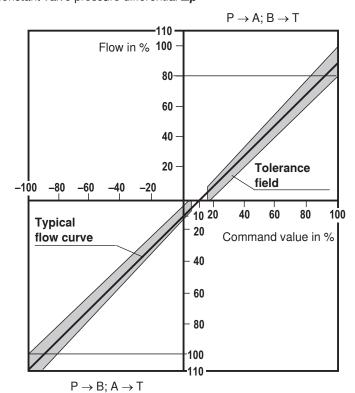
Valve	pressure	differential	in	bar	$\rightarrow$
· a. · ·	proceare	anno o o na		201	,

Ordering code	Rated flow	Curve
2	2 l/min	1
5	5 l/min	2
10	10 l/min	3
15	15 l/min	4
20	20 l/min	5
25	25 l/min	6

 $\Delta p$  = Valve pressure differential (inlet pressure  $p_P$  minus load pressure  $p_L$  minus return flow pressure  $p_T$ )

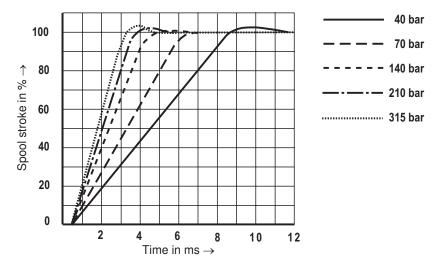
# Tolerance field of flow/signal function

at constant valve pressure differential  $\Delta p$ 

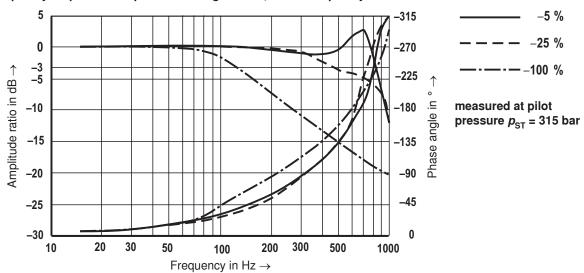


# Characteristic curves (measured with HLP32, $\vartheta_{oil}$ = 40 °C ± 5 °C)

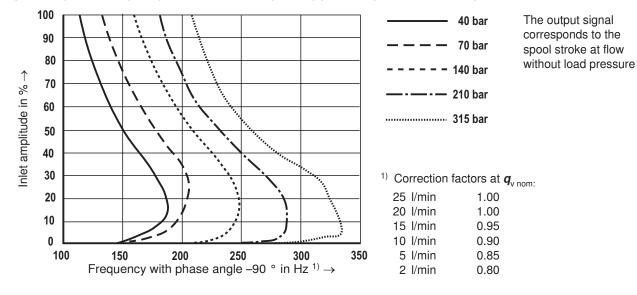
#### Transition function with pressure rating 315 bar, step response without flow



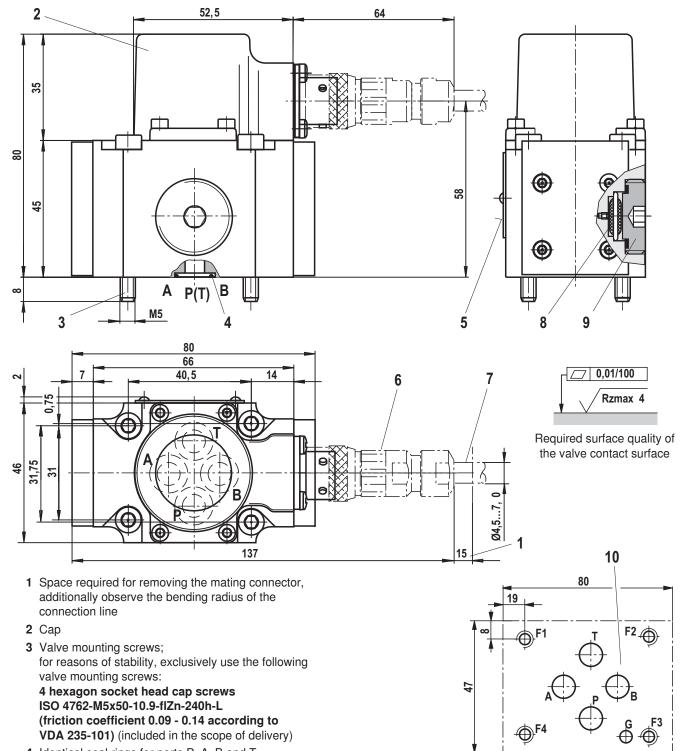
#### Frequency response with pressure rating 315 bar, stroke frequency without flow



# Dependency of the frequency f at -90 ° on the operating pressure p and the inlet amplitude



# **Dimensions** (Dimensions in mm)



4 Identical seal rings for ports P, A, B and T

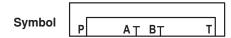
- 5 Name plate
- 6 Mating connector (separate order, see page 7)
- 7 Connection line, further information on page 7
- 8 Filter
- 9 Plug screw
- 10 Machined valve contact surface; porting pattern according to ISO 4401-03-02-0-05 (but without locating hole)

Subplates (separate order) with porting pattern according to ISO 4401-03-02-0-05, see data sheet 45100.

#### Notice:

Subplates are no components in the sense of directive 2014/34/EU and can be used after the manufacturer of the overall system has conducted an assessment of the risk of ignition. The "G...J3" versions are free from aluminum and/or magnesium and galvanized.

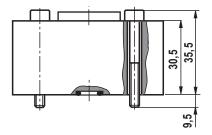
# Flushing plate with porting pattern according to ISO 4401-03-02-0-05 (dimensions in mm)



#### Ordering code and further information

- Material number: **R900936049**
- Weight: 0.6 kg
- Identical seal rings for ports P, A, B and T
- Mounting screws; for reasons of stability, exclusively use the following mounting screws:

4 hexagon socket head cap screws ISO 4762-M5x40-10.9-flZn-240h-L (friction coefficient 0.09 – 0.14 according to VDA 235-101) (included in the scope of delivery)



#### **Notice**

Before assembly and operation, please observe the information in the 29564-XN-B operating instructions.

# **Further information**

Subplates

Hydraulic fluids on mineral oil basis

Environmentally compatible hydraulic fluids

Flame-resistant, water-free hydraulic fluids

Flame-resistant hydraulic fluids - containing water (HFAE, HFAS, HFB, HFC)

Directional servo valve with mechanical position feedback

Selection of filters

Information on available spare parts

Data sheet 45100

Data sheet 90220

Data sheet 90221

Data sheet 90222

Data sheet 90223

Operating instructions 29564-XN-B

www.boschrexroth.com/filter

www.boschrexroth.com/spc

#### **Notes**

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